Not Recommended for New Designs

This product was manufactured for Maxim by an outside wafer foundry using a process that is no longer available. It is not recommended for new designs. The data sheet remains available for existing users.

A Maxim replacement or an industry second-source may be available. Please see the QuickView data sheet for this part or contact technical support for assistance.

For further information, contact Maxim’s Applications Tech Support.
Wideband Transconductance Amplifiers

General Description
The MAX435 and MAX436 are high-speed, wideband transconductance amplifiers (WTAs) with true differential, high-impedance inputs. Their unique architecture provides accurate gain without negative feedback, eliminating closed-loop phase shift — a primary cause of circuit oscillation in conventional high-speed amplifiers. The output of the WTA is a current that is proportional to the applied differential input voltage, providing inherent short-circuit protection for the outputs. Circuit gain is set by the ratio of two impedances and an internally set current gain factor (\(K\)).

The current output and the absence of negative feedback allow the differential output MAX435 to achieve a bandwidth of 275 MHz, an 800 V/\(\mu\)s slew rate, and a 1% settling time of 18 ns to a 0.5 V step input. The single-ended output MAX436 achieves a bandwidth of 200 MHz, an 850 V/\(\mu\)s slew rate, and a 1% settling time of 18 ns to a 0.5 V step input. Both amplifiers offer exceptional wideband common-mode rejection, with a CMRR of 53 dB at 10 MHz. 300 \(\mu\)V input offset voltage offers a level of DC precision rarely found in high-speed op amps.

Unlike current-feedback amplifiers, the MAX435/MAX436 have fully symmetrical, high-impedance inputs that tolerate wide differential input voltages without destructive failure or amplifier saturation, virtually eliminating overload recovery time. The unique performance features of these WTAs suit them for a wide variety of applications, such as high-speed instrumentation amplifiers and wideband, high-gain bandpass amplifiers. And, with its differential output, the MAX435 can be used in high-speed differential line driver and receiver applications.

Features
- 275 MHz Bandwidth (MAX435)
- 850 V/\(\mu\)s Slew Rate
- 18 ns Settling Time to 1%
- 53 dB CMRR at 10 MHz
- Low Noise, 7 nV/\(\sqrt{\text{Hz}}\) at 1 kHz
- No Feedback
- True Differential High-impedance Inputs
- Shutdown Capability: 450 \(\mu\)A (MAX435)

Ordering Information

<table>
<thead>
<tr>
<th>PART</th>
<th>TEMP. RANGE</th>
<th>PIN-PACKAGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>MAX435CPD</td>
<td>0°C to +70°C</td>
<td>14 Plastic DIP</td>
</tr>
<tr>
<td>MAX435CSD</td>
<td>0°C to +70°C</td>
<td>14 SO</td>
</tr>
<tr>
<td>MAX435CDO</td>
<td>0°C to +70°C</td>
<td>Dice*</td>
</tr>
<tr>
<td>MAX435EPD</td>
<td>-40°C to +85°C</td>
<td>14 Plastic DIP</td>
</tr>
<tr>
<td>MAX435ESD</td>
<td>-40°C to +85°C</td>
<td>14 SO</td>
</tr>
<tr>
<td>MAX435MD</td>
<td>-65°C to +125°C</td>
<td>14 CERDIP</td>
</tr>
</tbody>
</table>

Ordering Information continued on last page.
* Dice are specified at \(T_A = +25°C\), DC parameters only.

Pin Configurations

Typical Operating Circuits

For free samples & the latest literature: http://www.maxim-ic.com, or phone 1-800-998-8800
# Wideband Transconductance Amplifiers

**MAX4335/MAX4346**

### ABSOLUTE MAXIMUM RATINGS
- Total Supply Voltage (V+ to V−): 12V
- Positive Supply Voltage (V+ to GND): 6.0V
- Negative Supply Voltage (V− to GND): -6.0V
- Input Voltage: (-0.3V to V+ + 0.3V)
- Current Limit through Z+ or Z−: ±10mA
- Output Short-Circuit Duration: Continuous
- ISET Short-Circuit Duration (to GND or VEE): 1 sec
- Continuous Power Dissipation (TA = +70°C): 800mW

**SO** (derate 8.33mW/°C above +70°C): 867mW
**CERDIP** (derate 9.09mW/°C above +70°C): 727mW

**Operating Temperature Ranges:**
- MAX4335_1...
- MAX4335_E...
- MAX4343_M...

**Storage Temperature Range:**
- -65°C to +125°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### ELECTRICAL CHARACTERISTICS – MAX435

(V+ = 5V, V− = 0V, -2.5V ≤ IN ≤ 2.5V, ZL = 50Ω, Zs = 400Ω, Rs = 5.9kΩ, TA = +25°C, TJ = +25°C, unless otherwise noted. Specification is at +25°C junction temperature due to requirements of high-speed automatic testing. Actual values at operating temperatures may exceed the values at TJ = +25°C. No-load operating junction temperature may rise 30°C to 50°C above ambient.)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>SYMBOL</th>
<th>CONDITION</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating Supply Voltage</td>
<td>V+, V−</td>
<td>-55°C to +125°C</td>
<td>±4.75</td>
<td>±5.00</td>
<td>±5.25</td>
<td>V</td>
</tr>
<tr>
<td>Supply Current</td>
<td>I Shiv</td>
<td>-55°C to +125°C</td>
<td>30</td>
<td>35</td>
<td>41</td>
<td>mA</td>
</tr>
<tr>
<td>Input Voltage Range</td>
<td>IN+, IN−</td>
<td>-55°C to +125°C</td>
<td>-2.5</td>
<td>2.5</td>
<td>5</td>
<td>V</td>
</tr>
<tr>
<td>Input Offset Voltage</td>
<td>VOS</td>
<td>0.3</td>
<td>3.0</td>
<td>mV</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input Offset-Voltage Drift</td>
<td>AVOS/VΔT</td>
<td>3.5</td>
<td>3.0</td>
<td>μV/°C</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input Bias Current</td>
<td>IB</td>
<td>Tα = +25°C</td>
<td>1.0</td>
<td>3.0</td>
<td>μA</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>0°C to +70°C</td>
<td>5</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>-40°C to +85°C</td>
<td>10</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>-55°C to +125°C</td>
<td>10</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input Resistance</td>
<td>RN</td>
<td>200</td>
<td>800</td>
<td>kΩ</td>
<td></td>
<td></td>
</tr>
<tr>
<td>DC Resistance Looking into Z+ or Z−</td>
<td>RZ</td>
<td>0.15</td>
<td>1.50</td>
<td>Ω</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output Voltage Range</td>
<td>VOUT+, VOUT−</td>
<td>ZL = ZC = 50Ω</td>
<td>-3.5</td>
<td>3.5</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>Output Impedance</td>
<td>ROUT</td>
<td>2.0</td>
<td>3.5</td>
<td>kΩ</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output Current</td>
<td>IOUT</td>
<td>-10</td>
<td>10</td>
<td>mA</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Differential Output Offset Current</td>
<td>IOS, DIFF</td>
<td>Z+ and Z− are open, inputs are grounded</td>
<td>-140</td>
<td>0</td>
<td>140</td>
<td>μA</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Z+ and Z− are open, inputs are grounded</td>
<td>-100</td>
<td>-20</td>
<td>100</td>
<td>μA</td>
</tr>
<tr>
<td>Output Offset-Current Drift (either side)</td>
<td>AOS/VΔT</td>
<td>Z+ and Z− are open, inputs are grounded</td>
<td>2.3</td>
<td></td>
<td>μA/°C</td>
<td></td>
</tr>
<tr>
<td>Current Gain Ratio</td>
<td>K</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>A/A</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Tα = +25°C</td>
<td>3.90</td>
<td>4.00</td>
<td>4.10</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>0°C to +70°C</td>
<td>3.80</td>
<td>4.15</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>-40°C to +85°C</td>
<td>3.70</td>
<td>4.15</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>-55°C to +125°C</td>
<td>3.60</td>
<td>4.20</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Common-Mode Rejection Ratio</td>
<td>CMRR</td>
<td>At DC</td>
<td>70</td>
<td>90</td>
<td></td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>At 10MHz, ZL = 50Ω, ZC = 50Ω</td>
<td>53</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Power-Supply Rejection Ratio</td>
<td>PSRR</td>
<td>At DC</td>
<td>50</td>
<td>77</td>
<td></td>
<td>dB</td>
</tr>
<tr>
<td>Setting Time to 1%</td>
<td>tS</td>
<td>Zs = 200Ω, ZL = ZC = 25Ω</td>
<td>18</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>Slew Rate</td>
<td>SR</td>
<td>Zs = 200Ω, ZL = ZC = 25Ω</td>
<td>800</td>
<td></td>
<td>V/μs</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>Zs = 200Ω, ZL = ZC = 25Ω</td>
<td>550</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>-3dB Bandwidth</td>
<td>BW</td>
<td>Zs = 200Ω, ZL = ZC = 25Ω</td>
<td>275</td>
<td></td>
<td>MHz</td>
<td></td>
</tr>
<tr>
<td>Input Noise-Voltage Density</td>
<td>e0n</td>
<td>At 1kHz, single-ended input, Zs = 50Ω</td>
<td>7.0</td>
<td></td>
<td>nV/√Hz</td>
<td></td>
</tr>
</tbody>
</table>
## Wideband Transconductance Amplifiers

### Electrical Characteristics – MAX436

$(V_+ = 5V, V_- = -5V, 2.5V \leq IN_+ \leq 2.5V, 2.5V \leq IN_- \leq 2.5V, Z_L = 50\Omega, Z_L = 25\Omega, R_{	ext{EXT}} = 5.6\kappa\Omega, T_A = +25^\circ C, T_F = +25^\circ C$, unless otherwise noted. Specification is at $+25^\circ C$ junction temperature due to requirements of high-speed automatic testing. Actual values at operating temperatures may exceed the value at $T_F = +25^\circ C$. No-load operating junction temperature may rise $30^\circ C$ to $50^\circ C$ above ambient.)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Conditions</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating Supply Voltage</td>
<td>$V_+, V_-$</td>
<td>$-55^\circ C \text{ to } +125^\circ C$</td>
<td>±4.75</td>
<td>±5.00</td>
<td>±5.25</td>
<td>V</td>
</tr>
<tr>
<td>Supply Current</td>
<td>$I_S$</td>
<td>$-55^\circ C \text{ to } +125^\circ C$</td>
<td>30</td>
<td>35</td>
<td>41</td>
<td>mA</td>
</tr>
<tr>
<td>Input Voltage Range</td>
<td>$IN_+, IN_-$</td>
<td>$-55^\circ C \text{ to } +125^\circ C$</td>
<td>-2.5</td>
<td>2.5</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>Input Offset Voltage</td>
<td>$V_{OS}$</td>
<td></td>
<td>0.3</td>
<td>3.0</td>
<td>mV</td>
<td></td>
</tr>
<tr>
<td>Input Offset-Voltage Drift</td>
<td>$\Delta V_{OS}/\Delta T$</td>
<td>$T_A = +25^\circ C$</td>
<td>3.5</td>
<td>µV/C</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input Bias Current</td>
<td>$I_B$</td>
<td>$T_A = +25^\circ C$</td>
<td>1.0</td>
<td>3.0</td>
<td>µA</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>$0^\circ C \text{ to } +70^\circ C$</td>
<td>5</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>$-40^\circ C \text{ to } +85^\circ C$</td>
<td>10</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>$-55^\circ C \text{ to } +125^\circ C$</td>
<td>10</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input Resistance</td>
<td>$R_{IN}$</td>
<td>$Z_L = 500\Omega$</td>
<td>200</td>
<td>700</td>
<td>kΩ</td>
<td></td>
</tr>
<tr>
<td>DC Resistance Looking into $Z_+$ or $Z_-$</td>
<td>$R_Z$</td>
<td>$Z_L = 500\Omega$</td>
<td>0.15</td>
<td>1.50</td>
<td>Ω</td>
<td></td>
</tr>
<tr>
<td>Output Voltage Range</td>
<td>$V_{OUT_+, VOUT_-}$</td>
<td>$Z_L = 500\Omega$</td>
<td>-3.5</td>
<td>3.5</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>Output Impedance</td>
<td>$R_{OUT}$</td>
<td>$Z_L = 500\Omega$</td>
<td>2.0</td>
<td>3.3</td>
<td>kΩ</td>
<td></td>
</tr>
<tr>
<td>Output Current</td>
<td>$I_{OUT}$</td>
<td>$Z_L = 500\Omega$</td>
<td>-20</td>
<td>20</td>
<td>mA</td>
<td></td>
</tr>
<tr>
<td>Output Offset Current</td>
<td>$I_{OS}$</td>
<td>$Z_+ \text{ and } Z_- \text{ are open, inputs are grounded}$</td>
<td>-100</td>
<td>6</td>
<td>100</td>
<td>µA</td>
</tr>
<tr>
<td>Output Offset-Current Drift</td>
<td>$\Delta I_{OS}/\Delta T$</td>
<td>$Z_+ \text{ and } Z_- \text{ are open, inputs are grounded}$</td>
<td>0.75</td>
<td>µA/C</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Current Gain Ratio</td>
<td>$K$</td>
<td>$T_A = +25^\circ C$</td>
<td>7.8</td>
<td>8.0</td>
<td>8.2</td>
<td>A/A</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$0^\circ C \text{ to } +70^\circ C$</td>
<td>7.7</td>
<td>6.3</td>
<td></td>
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<tr>
<td></td>
<td></td>
<td>$-40^\circ C \text{ to } +85^\circ C$</td>
<td>7.6</td>
<td>8.3</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>$-55^\circ C \text{ to } +125^\circ C$</td>
<td>7.4</td>
<td>8.4</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Common-Mode Rejection Ratio</td>
<td>CMRR</td>
<td>At DC</td>
<td>70</td>
<td>84</td>
<td>dB</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>At 10MHz, $Z_I = 200\Omega$, $Z_L = 25\Omega$</td>
<td>53</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Power-Supply Rejection Ratio</td>
<td>PSRR</td>
<td>At DC</td>
<td>40</td>
<td>50</td>
<td>dB</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>At 10MHz, $Z_I = 200\Omega$, $Z_L = 25\Omega$</td>
<td>53</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Settling Time to 1%</td>
<td>$t_s$</td>
<td>$Z_I = 200\Omega$, $Z_L = 25\Omega$</td>
<td>18</td>
<td></td>
<td>ns</td>
<td></td>
</tr>
<tr>
<td>Slew Rate</td>
<td>$SR$</td>
<td>$Z_I$ shorted</td>
<td>850</td>
<td></td>
<td>V/µs</td>
<td></td>
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<tr>
<td></td>
<td></td>
<td>$Z_I$ shorted, $Z_L = Z_L = 25\Omega$</td>
<td>450</td>
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<td></td>
</tr>
<tr>
<td>-3dB Bandwidth</td>
<td>$BW$</td>
<td>$Z_I = 200\Omega$, $Z_L = 25\Omega$</td>
<td>200</td>
<td></td>
<td>MHz</td>
<td></td>
</tr>
<tr>
<td>Input Noise-Voltage Density</td>
<td>$e_n$</td>
<td>At 1kHz, single-ended input, $Z_I = 50\Omega$</td>
<td>7.0</td>
<td></td>
<td>nV/√Hz</td>
<td></td>
</tr>
</tbody>
</table>
Wideband Transconductance Amplifiers

**Typical Operating Characteristics**

**MAX435 MAX436**

**MAX435**
- **Common-Mode Rejection Ratio vs. Frequency**
- **Gain vs. Frequency**
- **Current Gain Ratio (K) vs. Temperature**

**MAX435**
- **Offset Voltage vs. Temperature**
- **Output Offset Current vs. Temperature**
- **Differential Output Offset Current vs. Temperature**

**MAX435**
- **Output Offset Current vs. Common-Mode Input Voltage**
- **Z Terminal Input Impedance vs. Temperature**
- **Input Bias Current vs. Temperature**
Wideband Transconductance Amplifiers

Typical Operating Characteristics (continued)

MAX435
INPUT IMPEDANCE vs. TEMPERATURE

V_{DD} = \pm 5V

MAX435
OUTPUT IMPEDANCE vs. TEMPERATURE

V_{DD} = \pm 5V

MAX435
MAXIMUM OUTPUT CURRENT vs. TEMPERATURE

V_{DD} = \pm 5V
R_{D1} = 5.9k\Omega

MAX435
SUPPLY CURRENT vs. TEMPERATURE

V_{DD} = \pm 5V
R_{D1} = 5.9k\Omega

MAX435
POWER-SUPPLY REJECTION RATIO vs. TEMPERATURE

V_{DD} = \pm 4.75V to 5.25V
V_{CS} = \pm 4.75V to 5.25V

MAXIM
Wideband Transconductance Amplifiers

Typical Operating Characteristics (continued)

MAX435/MAX4436

MAX435
COMMON-MODE REJECTION RATIO vs. TEMPERATURE

MAX435
MAXIMUM OUTPUT CURRENT vs. Rsref

MAX435
SUPPLY CURRENT vs. Rsref

MAX435
POWER DISSIPATION vs. Rsref

MAX435
MAXIMUM PACKAGE POWER DISSIPATION vs. TEMPERATURE

-60 -40 -20 0 20 40 60 80 100 120 140
TEMPERATURE (°C)

-30 0 10 20 30 40 50 60 70 80
OUTPUT CURRENT (mA)

-80 -60 -40 -20 0 20 40 60 80
SUPPLY CURRENT (mA)

0 10 20 30 40 50 60 70 80 90 100
POWER DISSIPATION (mW)

0 100 200 300 400 500 600 700 800
MAXIMUM PACKAGE POWER DISSIPATION (mW)

-80 -60 -40 -20 0 20 40 60 80 100 120 140
TEMPERATURE (°C)

MAXIM
Wideband Transconductance Amplifiers

Typical Operating Characteristics (continued)

MAX436
Common-Mode Rejection Ratio vs. Frequency

MAX436
Gain vs. Frequency

MAX436
Current Gain Ratio (K) vs. Temperature

MAX436
Offset Voltage vs. Temperature

MAX436
Output Offset Current vs. Temperature

MAX436
Output Offset Current vs. Common-Mode Input Voltage

MAX436
Z Terminal Input Impedance vs. Temperature

MAX436
Input Bias Current vs. Temperature

MAX436
Input Impedance vs. Temperature
Wideband Transconductance Amplifiers

Typical Operating Characteristics (continued)

- MAX436 Output Impedance vs. Temperature
- MAX436 Maximum Output Current vs. Temperature
- MAX436 Supply Current vs. Temperature
- MAX436 Power-Supply Rejection Ratio vs. Temperature
- MAX436 Common-Mode Rejection Ratio vs. Temperature
- MAX436 Maximum Output Current vs. Rs
- MAX436 Supply Current vs. Rs
- MAX436 Power Dissipation vs. Rs
- MAX436 Maximum Package Power Dissipation vs. Temperature
Wideband Transconductance Amplifiers

**Pin Description**

<table>
<thead>
<tr>
<th>PIN</th>
<th>MAX435</th>
<th>MAX436</th>
<th>NAME</th>
<th>FUNCTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>1, 12, 14</td>
<td>1, 12, 14</td>
<td>V+</td>
<td>Positive Power Supply (+5V)</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>2</td>
<td>IN+</td>
<td>Noninverting Amplifier Input</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>3</td>
<td>Z+</td>
<td>Positive Transconductance Terminal</td>
<td></td>
</tr>
<tr>
<td>4, 9</td>
<td></td>
<td>N.C.</td>
<td>No Connect - Leave this pin open</td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>5</td>
<td>Z-</td>
<td>Negative Transconductance Terminal</td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>6</td>
<td>IN-</td>
<td>Inverting Amplifier Input Terminal</td>
<td></td>
</tr>
<tr>
<td>7, 8, 10</td>
<td>7, 8, 10</td>
<td>V-</td>
<td>Negative Power Supply (-5V)</td>
<td></td>
</tr>
<tr>
<td>9</td>
<td></td>
<td>IOUT-</td>
<td>Inverting Differential Output</td>
<td></td>
</tr>
<tr>
<td>11</td>
<td>11</td>
<td>ISAT</td>
<td>Supply-Current Set Terminal</td>
<td></td>
</tr>
<tr>
<td>13</td>
<td></td>
<td>IOUT+</td>
<td>Noninverting Differential Output</td>
<td></td>
</tr>
<tr>
<td>-</td>
<td>13</td>
<td>IOUT-</td>
<td>Amplifier Output Terminal</td>
<td></td>
</tr>
</tbody>
</table>

**Theory of Operation**

The MAX435/MAX436 are wideband transconductance amplifiers (WTA) that operate with no feedback. These amplifiers are intrinsically stable since closed-loop phase shift does not affect amplifier stability. Unlike conventional voltage-mode amplifiers, WTAs need no compensation from an internally set dominant pole. Voltage-mode amplifiers require this pole to roll off open-loop gain and prevent oscillation from high-frequency phase shift.

The MAX435/MAX436’s unique architecture allows single-ended (MAX435) or differential (MAX436) signal gain to be set by the ratio of two impedances: the user-selected transconductance element or network (Zt), and the output load impedance (ZL). The WTAs are essentially voltage-controlled current sources, as shown in Figure 1.

The MAX435/MAX436’s output is a current proportional to the differential input voltage, and inversely proportional to the impedance of the user-selected transconductance element or network (Zt). The current output provides inherent short-circuit protection for the output terminals.

A differential input voltage (VIN) applied between the input terminals causes current to flow in the transconductance element (Zt). This current is equal to VIN/Zt. The current in the transconductance element is multiplied by the preset current gain (K) of the WTA, and appears at the output terminal(s) as a current equal to (K x VIN)/Zt. This current flows through the load impedance to produce an output voltage according to the following equation:

\[ V_{OUT} = K \frac{Z_L}{Z_t} \times V_{IN} \]

Where:
- \( K \) = WTA Current-Gain Ratio
- \( Z_L \) = Output Load Impedance
- \( Z_t \) = Transconductance Element Impedance
- \( V_{IN} \) = Differential Input Voltage

Unlike current-feedback amplifiers, the MAX435/MAX436 have symmetrical inputs with an input impedance of about 750kΩ. This allows true differential input applications to be realized, as shown in the MAX435 Typical Operating Circuit. And, because the input is symmetrical, opposite signal polarity can be obtained by swapping the input terminals.

With proper selection of component values, it is possible to implement an amplifier circuit that accepts differential input voltages covering the WTA’s entire input voltage range (-2.5V to +2.5V), without overloading its output stage. This characteristic makes the MAX435/MAX436 ideal for use in wideband instrumentation amplifiers, differential receivers, and settling-time measurement circuits.

**Design Procedure**

**Setting the Circuit Gain**

The MAX435/MAX436 produce an output current by multiplying a differential input voltage, \( V_{IN} \), by the transconductance, \( K/Z_t \). The voltage gain (AV) is set by the impedance of the transconductance network (Zt) and the output load impedance (ZL), according to the following formula:

\[ AV = K \left( \frac{Z_L}{Z_t} \right) \]

![Figure 1. a) MAX435 Operational Model. b) MAX436 Operational Model.](image-url)
Wideband Transconductance Amplifiers

The factor K in the gain equation refers to the WTA's current gain. K is factory trimmed to provide a low-drift, stable circuit gain for WTA applications. K is trimmed to $4.0 \pm 2.5\%$ for the MAX435, to $6.0 \pm 2.5\%$ for the MAX436.

The factor Z z in the gain equation is the impedance of a user-selected, 2-terminal transconductance element or network. This network is connected across the WTA's transconductance terminals, labeled as $Z_{+}$ and $Z_{-}$. The transconductance network should be selected, along with the output impedance, to provide the desired circuit gain and frequency shaping. To maintain linearity, the transconductance network should also be selected so that the current flowing through it, equal to $V_{in}/Z_{z}$, does not exceed 2.5mA under worst-case conditions of maximum input voltage and minimum transconductance element impedance ($Z_{o}$). Output current should not exceed $\pm10\text{mA}$ per output for the MAX435, or $\pm20\text{mA}$ for the MAX436.

Supply Current (ISET) Control

An external current source controls the WTA's internal current. Connecting an external resistor (RSET) from the ISET pin to the negative power supply ($V_{-}$) controls the current source. The typical value for this resistor is 5.9kΩ, which provides an output-current drive capability of $\pm10\text{mA}$ per output for the MAX435, $\pm20\text{mA}$ for the MAX436. Connect a 0.22μF ceramic capacitor from the ISET pin to $V_{+}$, to decouple the current source.

A larger resistor value will reduce the devices' supply current, power dissipation, and output-current drive capability. A smaller resistor value may also be used to increase the output-current capability, but take care that the power dissipation rating for the device package type is not exceeded for the specific circuit operating conditions. It is especially important to consider the maximum load current and ambient operating temperature of the circuit. Refer to the graphs in the Typical Operating Characteristics section for typical values of load current and power dissipation for different values of RSET.

Shutdown Mode

The WTA supply current varies with the value of RSET, but is relatively independent of the differential input voltage and the output load. The WTAs achieve much of their high-speed performance by maintaining a constant level of current within the internal transistors, and steering some of this current to the output when a differential input voltage is applied. To reduce power dissipation when the output load does not need to be actively driven, the ISET pin can be used to place the WTA into a low-power shutdown mode. If the ISET pin is disconnected from the RSET resistor and left open, the supply current of the MAX435 is reduced to approximately 450μA, while the supply current of the MAX436 is reduced to approximately 850μA. To reactivate the WTA, simply reconnect the ISET pin to the RSET resistor.

<table>
<thead>
<tr>
<th>PIN</th>
<th>RSET</th>
<th>Supply Current (μA Typ, +25°C)</th>
</tr>
</thead>
<tbody>
<tr>
<td>ISET (11)</td>
<td>Open (00)</td>
<td>MAX435: 450</td>
</tr>
</tbody>
</table>

DC Accuracy

The DC accuracy of circuits implemented with the MAX435/MAX436 is affected by several parameters, including:

1. Input Offset Voltage
2. Output Offset Current
3. Accuracy of WTA Current Gain Factor (K)
4. Tolerance of External Transconductance and Load Impedances

The input offset voltage of the WTA is caused by a mismatch of $V_{CS}$ voltages between the transistors in the amplifier input stage - the same mechanism that produces input offset voltages in ordinary bipolar amplifiers. The input offset voltage is measured as the voltage between the transconductance terminals (from $Z_{+}$ to $Z_{-}$), with each of the inputs ($IN_{+}$ and $IN_{-}$) grounded and no transconductance element in the circuit ($Z_{+}$ and $Z_{-}$ are open).

In an actual application circuit, the input offset voltage causes a current to flow in the transconductance element when no differential voltage is applied at the input terminals. This current is then multiplied by K to produce an error current at the output terminal(s).

A second source of DC error is the output offset current. This parameter is measured with no transconductance element in the circuit ($Z_{+}$ and $Z_{-}$ are open) and the input terminals ($IN_{+}$ and $IN_{-}$) grounded. Output offset current is the current that flows from an output terminal of the WTA under these conditions. The output offset current is the result of imperfect matching of devices in the output current mirror(s) of the WTA. The output current caused by the input offset voltage, as discussed previously, is NOT included in the Output Offset Current specification, since that component of the total output current will vary with the value of the transconductance element.
The finite output impedance also affects the amplifier gain. The output(s) are voltage-controlled current sources. An ideal current source would have an infinite output impedance, so that the output current would be independent of the load impedance. In practice, the MAX435/MAX436's output impedance is about 3.5kΩ.

As shown in Figure 2, the WTA output impedance (Rout) is paralleled with the circuit load impedance (RL), reducing the equivalent load impedance. After accounting for the finite WTA output impedance (Rout), the actual circuit gain is calculated with the following formula:

$$\frac{AV}{VIN} = \frac{K}{R_l} \left( \frac{Rout}{Rout + RL} \right)$$

The voltage gain error (ΔAV) with respect to the theoretical gain (AV = K x RL/Rl) is equal to:

$$\Delta AV = \frac{RL}{AV - RL + Rout}$$

**Power-Supply Bypassing and Board Layout**

Although the WTA architecture eliminates closed-loop phase shift as a source of circuit oscillation, careful high-frequency circuit design methods should be used to optimize the performance of WTA circuits.

Proper power-supply bypassing and board layout deserve careful attention. It is recommended that a ground plane be used with the MAX435/MAX436. The ground plane should include the entire portion of the PC board that is not dedicated to a specific signal trace.

Sockets are not recommended with the WTAs, because the additional pin-to-pin capacitance they introduce degrades wideband performance. Keep the length of traces connecting to the WTA input terminals as short as possible to minimize signal reflections and/or inductive coupling of high-frequency signals to the WTA. If the input signals must travel more than a few inches, use controlled impedance lines or coaxial cables; all signals should be properly terminated. Minimize the PCB pad
Wideband Transconductance Amplifiers

area for input connections, to prevent capacitive coupling of stray high-frequency signals.

Passive components used with the WTA should preferably be surface mount, to minimize stray inductance. If surface-mount components are not used, component lead lengths should be kept to an absolute minimum.

Bypass each power supply directly to the ground plane with a 0.22µF ceramic capacitor, placed as close to the supply pins as possible. Bypass the ISET pin with a 0.22µF ceramic capacitor to the V+ pin. Keep capacitor lead lengths as short as possible to minimize series inductance, surface-mount (chip) capacitors are ideal for this application.

Figure 7. Summing Amplifier

Capacitive Load Driving

Since the WTA requires no feedback, phase shift due to capacitive loading of the output will not degrade the circuit stability. The primary effect of capacitive loading is a reduction in output slew rate and bandwidth, which is limited by the rate at which the WTA output current can charge the capacitive load. Avoid capacitive coupling from the WTA output terminals to the input of transconductance terminals, since it introduces high-frequency feedback and possible oscillations.

Application Circuits

The WTA's unique architecture allows the implementation of many unique application circuits, some of which have been included here.

For the sake of clarity, bypass capacitors and the RSET resistor have not been shown in the following applications circuit schematics. The value of RSET is 5.9kΩ for every application circuit in Figures 3-16. For every application circuit in this data sheet, each power supply was bypassed to GND with a 0.22µF ceramic capacitor. The ISET pin was bypassed to V+ with a 0.22µF ceramic capacitor.
Wideband Transconductance Amplifiers

Coaxial Cable Drivers

To maximize power transfer and minimize distortion of high-speed signals, transmission lines must be terminated at the source and receiving ends with the characteristic impedance of the line itself. A 50Ω coaxial cable requires an impedance of 50Ω at each end for optimum performance.

With voltage-mode amplifiers, the transmitting end of a coaxial cable is typically back-terminated with a resistor in series with the amplifier output, since the voltage-mode amplifier's output has a very low impedance.

The WTA output is a current source, so its output impedance is relatively high (approximately 3.5kΩ). Therefore, when driving coaxial cables with the WTA, the back-termination resistor should be placed in parallel with the output impedance of the WTA, as shown in Figures 3 and 5. Note that back terminating cables in this manner will reduce the effective voltage gain of the circuit by a factor of 2.

The pulse response of the circuit in Figure 3 is shown in Figure 4, while Figure 6 is the pulse response of Figure 5's circuit.

Summing Amplifier

Two or more signals can be summed together by simply tying the output terminals of WTA's together as shown in Figure 7.

Lowpass Amplifier

A parallel RC network at the amplifier output will result in the lowpass amplifier circuit of Figure 8, with a -3dB corner frequency of:

\[ f_C = \frac{1}{2\pi (R_L)(C_L)} \]

The response of Figure 8's circuit with \( R_L = 100Ω \), \( C_L = 6.8nF \) and \( R_L = 25Ω \) is plotted in Figure 9.

Highpass Amplifier

A series RC network between the transconductance terminals, as shown in the circuit of Figure 10, will produce a highpass amplifier. The response of this circuit is plotted in Figure 11, for \( R_L = 100Ω \), \( C_L = 6.8nF \) and \( R_L = 25Ω \).
Wideband Transconductance Amplifiers

**Bandpass Amplifier**

Since there is no interaction between the transconductance network impedance and the output load impedance, poles and zeros in the WTA transfer function can be independently set by the two impedance networks. The circuit in Figure 12 is a bandpass amplifier, with the low corner frequency set by the impedance of the transconductance network. The high corner frequency is set by the impedance of the RC network at the amplifier output. The passband gain is \( K x \left( R_l/R_i \right) \).

Figure 13 is a plot of the response of the circuit in Figure 12, with \( R_i \approx 100\Omega, C_i = 20\mu F, R_L = 25\Omega \), and \( C_L = 395\mu F \).

**Tuned Amplifier**

The circuit in Figure 14 is a tuned amplifier circuit, tuned to the resonant frequency of the LC transconductance network, or

\[
\frac{1}{2 \pi L C} = \frac{1}{2 \pi R L C_i}
\]

The impedance of the transconductance network is a minimum at the resonant frequency, providing maximum amplifier gain at that frequency. The Q of the amplifier is a function of the parasitic components associated with the LC network. Figure 15 is the frequency response of the circuit in Figure 14, with \( L = 2.93\mu H \) and \( C_i = 9.9pF \).
Wideband Transconductance Amplifiers

The high-frequency gain of this circuit (beyond the resonant frequency) can be further reduced by increasing the load capacitance.

Crystal Tuned Amplifier

If a higher Q and more accurate control of the tuned amplifier frequency is required, a crystal can replace the tuned LC network as the WTA transconductance element, as shown in the "Crystal Tuned Amplifier" circuit of Figure 16. The crystal's impedance is a minimum at its resonant frequency, resulting in maximum gain for the amplifier circuit at that frequency.

The frequency response of Figure 16's circuit with a 25MHz crystal is shown in Figure 17.

Video Twisted-Pair Driver/Receiver Circuit

For distances less than about 5000 ft. (1500m), a single channel of baseband (composite) video can be transmitted with surprisingly high quality across twisted-pair cabling, leaving significant cost over traditional coaxial cabling. When using twisted pair as a transmission medium, two things are of highest importance: balanced (differential) transmission, to minimize common-mode noise, and proper termination to minimize reflections. The MAX435/MAX436, with 53dB CMRR at 10MHz and high input and output impedance, are well suited for this application.

Figure 18's circuit illustrates the MAX435 and MAX436 used as a driver/receiver circuit for twisted-pair video transmissions. One differential output MAX435 drives the balanced twisted pair from a ground-referred input signal, eliminating the need for a balun transformer or two single-ended output drivers.

Figure 16. Crystal Tuned Amplifier

Figure 17. Crystal Tuned Amplifier Gain vs. Frequency

Figure 18. Video Twisted Pair Driver/Receiver Circuit
Wideband Transconductance Amplifiers

The receiver circuit uses the single-ended output MAX436 for balanced to single-ended line conversion. The 100Ω resistor from IN+ to IN- provides proper line termination. The transconductance network (from Z+ to Z-) performs the gain adjustment (+6dB), as well as line equalization. Line equalization is sometimes required to boost the high-frequency gain of the receiver to account for the limited bandwidth of the twisted pair.

In Figure 18's circuit, compensation is achieved by adjusting R1 for proper brightness (to boost overall gain to compensate for ohmic losses), and C1 for best color (to add a zero/pole pair to extend the bandwidth). Since this equalization is done on the receiver end, the user simply views the screen and adjusts the controls for the best picture. For many NTSC applications, this line equalization may not be necessary, since the NTSC monitor performs a fair amount of loss equalization by calibrating the test patterns in the vertical interval test signal (VITS).

<table>
<thead>
<tr>
<th>PART</th>
<th>TEMP. RANGE</th>
<th>PIN-PACKAGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>MAX436CPD</td>
<td>0°C to +70°C</td>
<td>14 Plastic DIP</td>
</tr>
<tr>
<td>MAX436CSD</td>
<td>0°C to +70°C</td>
<td>14 SO</td>
</tr>
<tr>
<td>MAX436CD</td>
<td>0°C to +70°C</td>
<td>Dice*</td>
</tr>
<tr>
<td>MAX436EPD</td>
<td>-40°C to +85°C</td>
<td>14 Plastic DIP</td>
</tr>
<tr>
<td>MAX436ESE</td>
<td>-40°C to +85°C</td>
<td>14 SO</td>
</tr>
<tr>
<td>MAX436MJD</td>
<td>-55°C to +125°C</td>
<td>14 CERDIP</td>
</tr>
</tbody>
</table>

* Dice are specified at \( T_A = +25°C \), DC parameters only.

Chip Topography

TRANSISTOR COUNT: 230;
SUBSTRATE CONNECTED TO V-.